

A hierarchy of temporal logics with past

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Abstract

We extend the classical hierarchy of branching-time temporal logics between *UB* and *CTL** by studying which additional expressive power (if any) stems from the incorporation of past-time modalities. In addition, we propose a new temporal combinator, **N** for “From Now On”, that brings new and interesting expressive power. In several situations, nontrivial translation algorithms exist from a temporal logic with past to a pure-future fragment. These algorithms have important practical applications, e.g., in the field of model-checking.

0. Introduction

Temporal logics have long been recognized as a very convenient formalism with which to reason about concurrent and reactive systems [8, 21]. In computer science, most theoretical studies of temporal logics only use future-time constructs. This is in contrast with the temporal logics studied by linguists, philosophers, ..., where past-time and future-time have been on an equal footing [23].

This situation is surprising because computer scientists recognize that past-time constructs can be very useful when it comes to express certain properties. For example, using “ \square ” for “at all future moments” and “ \diamond^{-1} ” for “at some past moment”, it is easy to state that “in all cases the occurrence of a problem must have been preceded by a cause”, i.e., “no problem will ever occur without a cause”, which is an important safety property one often uses (under some form). One just writes:

$$\square(\text{problem} \Rightarrow \diamond^{-1}\text{cause}) \quad (1)$$

Finally, the usefulness of past-time constructs is most apparent in the classification of temporal properties [28, 20, 5].

However, it has been shown that formulas using past-time constructs can often be replaced by equivalent *pure-future* formulas [13, 18]. For example, (1) is equivalent to

$$\neg(\neg\text{cause} \mathbf{U} \text{problem}) \quad (2)$$

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which uses the “Until” construct U . (We state in the next section in which formal sense these two formulas are equivalent.) The underlying motto is that *past-time brings additional expressivity from a practical, but not from a theoretical viewpoint*. Clearly, a formulation like (1) is much more natural than the clumsier (2). This is even more obvious when one tries to express a statement like $\Box(\text{problem} \Rightarrow \Diamond^{-1}(\text{cause1} \wedge \Diamond^{-1} \text{cause2}))$ without past-time.

Another reason why past-time is often omitted in theoretical studies is that very efficient model-checking algorithms exist for state-based logics like CTL (with or without fairness) [8, 7], while it is not clear how to adapt this technology to (history-based) logics with past. Some existing results (e.g. [15]) consider model-checking for PTL with past, but this problem is already PSPACE-complete for pure-future PTL [24].

This raises the following question: “*Is it possible to combine the great convenience of past-time for specification with the efficiency of CTL model-checking for verification?*” Rather than try to adapt the existing technology to, e.g., $CTL + \text{Past}$, which we believe is a very difficult problem, we argue that a translation-based approach is feasible [16]. By only requiring the addition of a translating interface, such an approach would allow to reuse the very efficient model-checking tools that have been built after years of improvement [3]. Of course, this approach requires the use of a logic with past that can be translated into, e.g., CTL .

When we surveyed the available *past-elimination results* in the literature, we found:

- $PTL + \text{Past}$ can be translated into PTL [13, 12]. This is the standard result in the field.
- The linear-time propositional μ -calculus, $L\mu + \text{Past}$ can be translated into the usual pure-future μ -calculus [26].¹
- $CTL^* + \text{Past}$ can be translated into CTL^* [14]. This is a simple corollary of Gabbay’s proof for PTL .
- $PTL \setminus X + \text{Past}$ can be translated into $PTL \setminus X$ [22]. This uses rewrite rules similar to Gabbay’s rules.

Finally, apart from [26] all of these (and some more, e.g. [4]) are just variants of Gabbay’s result for PTL . And they do not solve our problem. For example, if we want to add past-time constructs to a (state-based) branching-time logic-like CTL , the literature only tells us how to translate $CTL + \text{Past}$ into CTL^* . This is not satisfactory, for we consider CTL precisely because it admits a very efficient model-checking procedure, while this is not the case with CTL^* . Therefore, knowing that $CTL + \text{Past}$ can be translated into CTL would be, from a practical viewpoint, a very interesting addition to the results we mentioned.

This is exactly what we investigate in this article. We address general questions of the form “*Which past-time combinators can be added to branching-time temporal logics like CTL , $ECTL$, ... without compromising the possibility to translate back*

¹ In fact, [26] gives a translation from some kind of backward-and-forward Büchi automata into usual Büchi automata, so that one has to translate from the μ -calculus into Büchi automata, and *vice versa*.

into CTL, ECTL, ... ?” We consider the classical branching-time hierarchy from UB to CTL* [10, 11] and systematically try to add past-time constructs.

A second motivation for this study is the introduction of a new temporal combinator, “N” for “From Now On” or “Henceforth”. N is very useful in some situations where we want to restrict the scope of past-time combinators. This new combinator can also be eliminated (i.e., translated into pure-future constructs) in some situations.

Here is the plan of the article: we define PCTL* (CTL* + Past) in Section 1, and the relevant fragments (PTL, CTL, ...) in Section 2. Section 3 discusses and motivates *initial equivalence*, the correctness criterion we use for our expressivity problems. Then Sections 4 and 5 state fundamental expressivity results of past-time combinators in branching-time logics. The new “From Now On” combinator is motivated and introduced in Section 6 where our expressivity results are extended. Some proofs have been relegated to an Appendix when they disturb the exposition.

1. Temporal logics with Past

1.1. Syntax

We define PCTL* (for “CTL* with Past”) as an extension of CTL* [11] with past-time combinators. (Our definition differs slightly from the PCTL* used in [14] as we explain later.) We assume a given set Prop = {a, b, ..., problem, cause, ...} of *atomic propositions*.

Definition 1.1 (*Syntax of PCTL**). The formulas of PCTL* are given by the following grammar

$$PCTL^* \ni f, g ::= a \mid f \wedge g \mid \neg f \mid E f \mid f U g \mid X f \mid f S g \mid X^{-1} f$$

where $a \in Prop$.

Here S is the “Since” combinator, a past-time variant of U (“Until”). X^{-1} is “Previously”, a past-time variant of X (“Next”). We use the standard abbreviations $\top, \perp, f \vee g, f \Leftrightarrow g, \dots$ and

$$\begin{array}{lll} F f \stackrel{\text{def}}{=} \top U f & F^{-1} f \stackrel{\text{def}}{=} \top S f & A f \stackrel{\text{def}}{=} \neg E \neg f \\ G f \stackrel{\text{def}}{=} \neg F \neg f & G^{-1} f \stackrel{\text{def}}{=} \neg F^{-1} \neg f & F^{\infty} f \stackrel{\text{def}}{=} G F f \\ & & G^{\infty} f \stackrel{\text{def}}{=} F G f \end{array} \quad (3)$$

F and G corresponds to the \diamond and \square notations sometimes used in modal logics. In PCTL*, (1) is written $G(\text{problem} \Rightarrow F^{-1} \text{cause})$.

Though we did not make the usual (unnecessary) distinction between “state” and “path” formulas, PCTL* includes as fragments the CTL and CTL* branching-time

temporal logics, as well as the *PTL* linear-time temporal logic. In all the following, “a logic” means “a fragment of *PCTL**”.

A *pure-future formula* is a formula in which no X^{-1} and **S** occur. Then *CTL** is the fragment of *PCTL** containing all pure-future formulas. A *state formula* is a pure-future formula that starts with a **A** or **E** quantifier. A *linear-time formula* is a formula without any **E** (or **A**) quantifier.

1.2. Semantics

Temporal logics are interpreted in Kripke structures:

Definition 1.2. A *Kripke structure* S is a tuple $S = \langle Q_S, R_S, l_S \rangle$, where $Q_S = \{p, q, \dots\}$ is a set of *states*, $R_S \subseteq Q_S \times Q_S$ is a total² *accessibility relation*, and $l_S: Q_S \rightarrow 2^{Prop}$ is a labeling of the states with propositions.

A *run* in a structure S is any infinite sequence of states $q_0.q_1 \dots$ s.t. $q_i R q_{i+1}$ for $i = 0, \dots$. We write $\Pi_S(q) = \{\pi, \dots\}$ for the set of all runs (in S) starting from q , and $\Pi(S)$ for the set of all runs in S . For any i , $\pi(i) \stackrel{\text{def}}{=} q_i$, $\pi^i \stackrel{\text{def}}{=} q_i.q_{i+1} \dots$, and $\pi_{|i} \stackrel{\text{def}}{=} q_0.q_1 \dots q_{i-1}$ are resp. the i th state, the i th suffix and the i th prefix of π .

A *PCTL** formula expresses properties of a moment in a run. Formally, we define, for any $\pi \in \Pi(S)$ and any $n = 0, 1, 2, \dots$ when a formula $f \in PCTL^*$ is true of run π at time n , written $\pi, n \models_S f$. We often drop the “ S ” subscript when it is clear from the context.

Definition 1.3 (*Semantics of PCTL**). We define $\pi, n \models_S f$ by induction on the structure of f :

- $\pi, n \models a$ iff $a \in l(\pi(n))$,
- $\pi, n \models f \wedge g$ iff $\pi, n \models f$ and $\pi, n \models g$,
- $\pi, n \models \neg f$ iff $\pi, n \not\models f$,
- $\pi, n \models E f$ iff there exists a $\pi' \in \Pi(S)$ with $\pi'_{|n} = \pi_{|n}$ s.t. $\pi', n \models f$,
- $\pi, n \models f U g$ iff there is a $k \geq n$ s.t. $\pi, k \models g$ and $\pi, i \models f$ for all $n \leq i < k$,
- $\pi, n \models X f$ iff $\pi, n + 1 \models f$,
- $\pi, n \models f S g$ iff there is a $0 \leq k \leq n$ s.t. $\pi, k \models g$ and $\pi, i \models f$ for all $k < i \leq n$,
- $\pi, n \models X^{-1} f$ iff $n > 0$ and $\pi, n - 1 \models f$.

Informally, $\pi(n)$ is the present state. The prefix $\pi_{|n}$ is the past and π^n is a selected future. a means “ a holds now”, $f U g$ means “ g will hold at some point in the (selected) future, and f holds in the meantime”, $X f$ means “ f holds at the next moment”, $X^{-1} f$ means “ f did hold at the previous moment”, $f S g$ means “ g did hold in the past and f has been holding ever since that moment”, $E f$ means that “the present admits a

² Restricting to structures with a total accessibility relation is a technical simplification that does not change any of our expressivity results.

possible future for which f holds”, $\overset{\infty}{\mathbf{F}} f$ means that “ f will hold infinitely many times in the (selected) future” and $\overset{\infty}{\mathbf{G}} f$ means that “ f will hold at all but finitely many times in the (selected) future”.

This semantics is *Ockhamist* [23,27] in the sense that it views the past as *fixed* (and finite) and only considers nondeterminism in the future. This is in contrast with e.g. the *CTL**+Past from [25] where it is possible to quantify over all potential ways of reaching a given state. We claim that the Ockhamist viewpoint is more suited to the specification of reactive systems behaviour, because it considers states in a computation tree, while the non-Ockhamist viewpoints consider machine states (where past is not very meaningful).

Notice also that our semantics considers a *cumulative past*, where the history of the current situation increases with time and is never forgotten. This contrasts with the definition from [14] where one has

$$\pi, n \models \mathbf{E} f \text{ iff there is a } \pi' \in \Pi(\pi(n)) \text{ s.t. } \pi', 0 \models f$$

We believe our definition is more natural and, because a non-cumulative past is sometimes handy, we present in Section 6 a larger logic, *NCTL**, which allows both viewpoints.

Now for a formula f we define derived truth concepts:

$$\begin{aligned} \pi \models_S f &\stackrel{\text{def}}{\iff} \pi, 0 \models_S f && \text{reads “run } \pi \text{ satisfies } f\text{”} \\ q \models_S f &\stackrel{\text{def}}{\iff} \pi \models_S f \text{ for all } \pi \in \Pi(q) && \text{“state } q \text{ satisfies } f\text{”} \\ S \models f &\stackrel{\text{def}}{\iff} \pi \models_S f \text{ for all } \pi \in \Pi(S) && \text{“structure } S \text{ satisfies } f\text{”} \\ \models_g f &\stackrel{\text{def}}{\iff} \pi, n \models_S f \text{ for all } (\pi, n) && \text{“} f \text{ is (globally) valid”} \\ &&& \text{in all Kripke structures } S \\ \models_i f &\stackrel{\text{def}}{\iff} S \models f \text{ for all Kripke structures } S && \text{“} f \text{ is (initially) valid”} \end{aligned}$$

$\models_g f$ entails $\models_i f$ but the converse is not true, and in fact $\models_g f$ iff $\models_i \mathbf{G}f$. As indicated by our definition of $S \models f$, it is the “ \models_i ”, so-called anchored [19], notion of validity that interests us here, as is usual in computer science [8].

The following proposition is a formal justification that an Ockhamist viewpoint is sensible.

Proposition 1.4. *Two states q, q' (in a finite Kripke Structure) satisfy the same *PCTL** formulas iff they are bisimilar.*

This generalizes Theorem 3.2 of [2] where a formal definition of the well-known notion of bisimilarity can be found. The proof is an easy corollary of our Theorem 3.12. In general, this proposition does not hold for logics with a non-Ockhamist viewpoint.

Definition 1.5. (1) We say that two formulas f and g are *equivalent*, written $f \equiv g$, when for all (π, n) in all structures, $\pi, n \models f$ iff $\pi, n \models g$.

(2) We say that f and g are *initially equivalent*, written $f \equiv_i g$, when for all π in all structures, $\pi \models f$ iff $\pi \models g$.

Thus $f \equiv g$ when $\models_g f \Leftrightarrow g$, and $f \equiv_i g$ when $\models_i f \Leftrightarrow g$. Clearly, $f \equiv g$ entails $f \equiv_i g$ but the converse is not true. Here is a simple example: $X^{-1}\top \equiv_i \perp$ because no run satisfies $X^{-1}\top$ at its starting point. But of course $X^{-1}\top \not\equiv \perp$ because for any run π with length at least 2, we have $\pi, 1 \models X^{-1}\top$. Similarly, $\mathbf{G}(\text{problem} \Rightarrow \mathbf{F}^{-1}\text{cause})$ is initially equivalent and not globally equivalent to (2).³

When we use temporal logics to reason about programs, it is customary to consider initial validity as the basic concept. Specifications refer to the runs of a program, starting from some initial states. Therefore, we are content to replace a given formula f by an equivalent f' , using “initial equivalence” as the relevant notion. The interest with global equivalence is that it is substitutive: if $f \equiv f'$ then f can be replaced by f' in any temporal context, yielding equivalent formulas. That is, \equiv is a congruence w.r.t. all temporal combinators. On the other hand, \equiv_i is only a congruence w.r.t. boolean combinators (and X^{-1} and \mathbf{S}).

Considering initial equivalence as the correctness criterion allows to eliminate past-time combinators, according to

$$\begin{aligned} X^{-1}f &\equiv_i \perp, \\ f\mathbf{S}g &\equiv_i g. \end{aligned} \tag{4}$$

but, because \equiv_i is not substitutive in temporal contexts, these simplification rules cannot be used in all situations.

2. A menagerie of temporal logics

Many fragments of CTL^* have been used and investigated. In fact, CTL^* was first proposed as a logic which included all other previously proposed temporal logics. Emerson and Halpern introduced a very convenient device to denote such fragments. Following them, we write $B(C, \dots)$ the fragment of CTL^* where C, \dots are the only allowed linear-time combinators, and where every occurrence of a linear-time combinator must be under the immediate scope of an \mathbf{E} or \mathbf{A} quantifier (the “ B ” is for “branching”). For example:

- $B(\mathbf{X}, \mathbf{F})$ is the UB logic from [1]. $\mathbf{AFX}a$ is not in UB while $\mathbf{AFAX}a$ is.
- $B(\mathbf{X}, \mathbf{U})$: This is the CTL logic from [6]. $\mathbf{A}[a \mathbf{U} \mathbf{EX}b]$ is in CTL but not in UB where only \mathbf{F} and \mathbf{X} can be used.
- $B(\mathbf{X}, \mathbf{U}, \mathbf{F})$: This is the $ECTL$ (“Extended CTL ”) logic from [11]. $\mathbf{E} \overset{\infty}{\mathbf{F}} a$ is in $ECTL$ but not in CTL .

³ To be precise (2) is not sufficient. $\mathbf{G}(\text{problem} \Rightarrow \mathbf{F}^{-1}\text{cause}) \equiv_i \neg(\neg\text{cause} \mathbf{U} (\text{problem} \wedge \neg\text{cause}))$ is correct.

$B(C, \dots, \neg, \wedge)$ denotes a fragment enlarging $B(C, \dots)$ inasmuch as it allows boolean combinators to appear between the linear-time combinators C, \dots and the branching-time quantifier on top of it. For example:

- $B(X, F, \neg, \wedge)$ (also called UB^+) allows $E[Fa \wedge Fb \Rightarrow Xc]$.
- $B(X, U, \neg, \wedge)$ (also called CTL^+) allows $A[(a U b) \vee Xc]$.
- $B(X, U, F, \neg, \wedge)$ is the $ECTL^+$ logic that roughly corresponds to the CTF logic introduced in [9].

Now, because for any branching-time formulas f, g, \dots we have $EX^{-1}f \equiv X^{-1}f$, $E(fSg) \equiv fSg$, etc., we do not enforce the use of a E or A immediately on top of past-time combinators in a $B(C, \dots)$ fragment. For example, we consider that $X^{-1}(E(F^{-1}a)U F^{-1}b)$ is a $B(U, X^{-1}, S)$ formula.

This (syntactic) classification of relevant fragments of $PCTL^*$ can be linked to semantic notions through the following

Definition 2.1.

- A formula f is a *future-formula* iff the truth of f at (π, n) in S only depends on the future $\pi(n)\pi(n+1)\dots$, i.e. if $\pi^n = \pi'^m$ implies $\pi, n \models_S f \Leftrightarrow \pi', m \models_S f$.
- f is a *present-formula* iff the truth of f at (π, n) in S only depends on the current state, i.e. if $\pi(n) = \pi'(m)$ implies $\pi, n \models_S f \Leftrightarrow \pi', m \models_S f$
- f is a *branching-time formula* iff the truth of f at (π, n) in S does not depend of the selected future, i.e. if $\pi(0)\dots\pi(n) = \pi'(0)\dots\pi'(m)$ implies $\pi, n \models_S f \Leftrightarrow \pi', m \models_S f$.

Clearly, any present-formula is a future-formula and a branching formula.

- Proposition 2.2.** (1) Any pure-future formula is a future-formula.
 (2) Any state formula is a present-formula.

Proposition 2.3. A logic of the form $B(C, \dots, \neg, \wedge)$ only contains branching-time formulas.

3. Compared expressivity

When we discuss comparative expressivity between two temporal logics L_1 and L_2 , two notions can be used:

Definition 3.1. (1) L_1 is *less*⁴ expressive than L_2 , written $L_1 \preceq_g L_2$, if for any $f_1 \in L_1$ there is a $f_2 \in L_2$ s.t. $f_1 \equiv f_2$.

⁴ or equally ...

(2) L_1 is *initially less expressive* than L_2 , written $L_1 \preceq_i L_2$, if for any $f_1 \in L_1$ there is a $f_2 \in L_2$ s.t. $f_1 \equiv_i f_2$.

Clearly, $L_1 \subseteq L_2$ implies $L_1 \preceq_g L_2$. Also, $L_1 \preceq_g L_2$ implies $L_1 \preceq_i L_2$. In both cases the converse is not true in general. As usual we denote by “ \prec_* ” and “ \equiv_* ” the strict ordering and the equivalence relation induced by “ \preceq_* ”.

Also, for pure-future logics, both “ \preceq_g ” and “ \preceq_i ” coincide. For pure-future logics, the classical hierarchy result has been established in [10, 11]:

$$UB \prec UB^+ \prec CTL \equiv CTL^+ \prec ECTL \prec ECTL^+ \prec CTL^*$$

When logics with past-time are considered, the most relevant result is the Separation Theorem for *PTL*.

Theorem 3.2 (Gabbay [13]). *Any PPTL formula can be rewritten into an equivalent totally separated formula (that is, a boolean combination of pure-past and pure-future PPTL formulas.)*

See [12] for a proof. The immediate corollary is

Corollary 3.3. *PPTL \equiv_i PTL.*

Proof. With totally separated formulas, (4) allows to fully remove past-time constructs (modulo \equiv_i). \square

There is a branching-time equivalent to this last result:

Theorem 3.4 (Hafer and Thomas [14]). *PCTL* \equiv_i CTL*.*

(The proof in [14] applies to their definition of *PCTL** but it can be adapted without any difficulty to our definition.)

4. Temporal logics with X^{-1} and S

Let us write *PCTL* for “*CTL + Past*”, i.e. $B(X, U, X^{-1}, S)$. The question which initiated our study was “*does PCTL \equiv_i CTL?*”. The answer is unfortunately:

$$PCTL \not\equiv_i CTL$$

This section investigates why.

One problem is that the simple addition of X^{-1} gives a logic which cannot be (initially) less expressive than *ECTL⁺* which is the largest relevant fragment of *CTL** for which efficient model-checking exists.

Theorem 4.1. *ECTL⁺ $\not\equiv_i$ B(F, X⁻¹).*

Proof. The CTL^* formula $EG(a\forall Xa)$ has no $ECTL^+$ equivalent [11] but it is initially equivalent to the $B(F, X^{-1})$ formula $EG(a\forall X^{-1}a\forall \neg X^{-1}\top)$. \square

The simple addition of S brings similar problems.

Theorem 4.2. $ECTL^+ \not\equiv_i UB + S \stackrel{\text{def}}{=} B(X, F, S)$.

Proof. The CTL^* formula $E(s\forall aUb)Ur$ has no $ECTL^+$ equivalent but it can be written (modulo \equiv_i) in $UB + S$. See the Appendix. \square

The F combinator of UB is necessary here and for example, one has

Theorem 4.3. $B(X, X^{-1}, S) \equiv_i B(X)$.

Proof. See the Appendix. \square

In some way, these negative results rely on the fact that our semantics considers the past as fixed so that X^{-1} and S can express properties which usually can only be expressed in a linear-time framework. However, adopting a non-Ockhamist viewpoint would make things even worse since no translation can be expected if Proposition 1.4 does not hold.

5. Temporal logics with F^{-1}

When we consider the F^{-1} past-time combinator alone, the problems we had with X^{-1} and S do not occur.

Theorem 5.1. $CTL + F^{-1} \stackrel{\text{def}}{=} B(X, U, F^{-1}) \equiv_i CTL$.

This result is fundamental. The crucial step in the proof is to establish the following lemma.

Lemma 5.2 (Separation lemma for $CTL + F^{-1}$). *Any $CTL + F^{-1}$ formula is (globally) equivalent to a separated $CTL + F^{-1}$ formula.*

Here a (partially) *separated* formula is a formula where no past-time combinator occurs under the scope of a future-time combinator.⁵ Once a $CTL + F^{-1}$ formula has been separated, (4) can be applied to eliminate all past-time constructs. (See the Appendix for a proof of Lemma 5.2.)

⁵ Observe that the usual notion of (totally) separated formula used for linear-time logics will not work in our branching-time framework.

The previous theorem shows how one can extend *CTL* with past-time constructs without loosing the ability to translate back into *CTL*. This must be done precisely. Adding F^{-1} will do, adding X^{-1} or S will fail. F^{-1} is a specialization of S but it is nonetheless sufficient in many situations. For example, (1) is written in $CTL + F^{-1}$.

F^{-1} can be added to other logics as well. We have

Theorem 5.3. $CTL^+ + F^{-1} \stackrel{\text{def}}{=} B(X, U, F^{-1}, \neg, \wedge) \equiv_i CTL$.

A similar result exists for $ECTL^+$:

Theorem 5.4. $ECTL^+ + F^{-1} \stackrel{\text{def}}{=} B(X, U, \overset{\infty}{F}, F^{-1}, \neg, \wedge) \equiv_i ECTL^+$.

Adding F^{-1} to *ECTL* increase the expressive power:

Theorem 5.5. $ECTL^+ \succ_i ECTL + F^{-1} \succ_i ECTL$.

Proof. Modulo \equiv_i , the $ECTL + F^{-1}$ formula $\overset{\infty}{E}F(a \wedge G^{-1}b)$ cannot be expressed in *ECTL*, and the $ECTL^+$ formula $\overset{\infty}{E}(F a \wedge \overset{\infty}{F} b)$ cannot be expressed in $ECTL + F^{-1}$. See the Appendix. \square

6. A combinator for From Now On

We introduce a new unary combinator, N , for “From Now On”⁶ or “Henceforth”, in our *PCTL** logic and write $NCTL^*$ for the logic $PCTL^* + N$.

The semantics of N is given by

$$\pi, n \models Nf \text{ iff } \pi^n, 0 \models f$$

That is, Nf holds if f holds when we forget the past, or if “from now on f holds”. Here is an example motivating this new construct. Assume we want to state that $AG(\text{problem} \Rightarrow F^{-1}\text{cause})$ holds as soon as a proper reset had been done. We can write

$$AG[\text{reset} \Rightarrow AG(\text{problem} \Rightarrow F^{-1}\text{cause})] \tag{5}$$

Then, if a problem occurs after a proper reset, there must have been a cause, *but the cause may have occurred before the reset*. If we want to specify that every time there is a reset, *then from now on* no problem can occur without a cause (i.e., a cause occurring after the reset), we can write:

$$AG[\text{reset} \Rightarrow NAG(\text{problem} \Rightarrow F^{-1}\text{cause})] \tag{6}$$

⁶No connection with the Now of H. Kamp, Formal properties of ‘now’, *Theoria*, 227–263, 1971.

The difference between (5) and (6) is important. It exemplifies the interest of having \mathbf{N} . With \mathbf{N} we can encode the definition for \mathbf{E} used in [14]: their $\mathbf{E}f$ is equivalent to our $\mathbf{N}\mathbf{E}f$. Then, the $PCTL^*$ logic of [14] can express (6). But it cannot express (directly) (5). In our experience, both constructs are useful, and that's why we propose a specific combinator.

Finally, \mathbf{N} is very useful to characterize key semantic properties:

Proposition 6.1. *A $NCTL^*$ formula f is a future-formula iff $f \equiv \mathbf{N}f$.*

and to explain the difference between *initial* and *global* validity:

Proposition 6.2. $\models_i f$ iff $\models_g \mathbf{N}f$.

Basic properties of \mathbf{N} are:

Proposition 6.3. *For all $NCTL^*$ formulas f, g :*

- $\mathbf{N}(f \wedge g) \equiv \mathbf{N}f \wedge \mathbf{N}g$ and $\mathbf{N}\neg f \equiv \neg \mathbf{N}f$,
- $\mathbf{N}\mathbf{E}f \equiv \mathbf{E}\mathbf{N}f$ and $\mathbf{N}\mathbf{N}f \equiv \mathbf{N}f$,
- $\mathbf{N}\mathbf{X}^{-1}f \equiv \perp$,
- $\mathbf{N}(f\mathbf{S}g) \equiv \mathbf{N}g$, *entailing* $\mathbf{N}\mathbf{F}^{-1}f \equiv \mathbf{N}f$.

Formulas using \mathbf{N} can be translated into equivalent (often longer) formulas without \mathbf{N} :

Theorem 6.4. $NCTL^* \equiv PCTL^* \equiv_i CTL^*$.

Proof. This is a simple extension of Theorem 3.4. The new point is to eliminate \mathbf{N} : consider $\mathbf{N}f$ with $f \in PCTL^*$ and rewrite f into a separated f' . Then $\mathbf{N}f'$ can be rewritten into some $PCTL^*$ formula thanks for Propositions 6.2 and 6.3. \square

Similarly, we can extend Theorems 5.1 and 5.4 into

Theorem 6.5. $CTL^+ + \mathbf{F}^{-1} + \mathbf{N} \stackrel{\text{def}}{=} B(\mathbf{X}, \mathbf{U}, \mathbf{F}^{-1}, \mathbf{N}, \neg, \wedge) \equiv_i CTL$.

Theorem 6.6. $ECTL^+ + \mathbf{F}^{-1} + \mathbf{N} \stackrel{\text{def}}{=} B(\mathbf{X}, \mathbf{U}, \overset{\infty}{\mathbf{F}}, \mathbf{F}^{-1}, \mathbf{N}, \neg, \wedge) \equiv_i ECTL^+$.

Proof. Like Theorems 5.1 and 5.4. In both cases, occurrences of \mathbf{N} are easy to simplify because we deal with separated formulas. \square

\mathbf{N} is not only a notational facility. It sometimes (strictly) adds expressive power. For example, writing PUB for $UB + \mathbf{X}^{-1} + \mathbf{F}^{-1} \stackrel{\text{def}}{=} B(\mathbf{X}, \mathbf{F}, \mathbf{X}^{-1}, \mathbf{F}^{-1})$, we have $UB \prec_i PUB \prec_i$

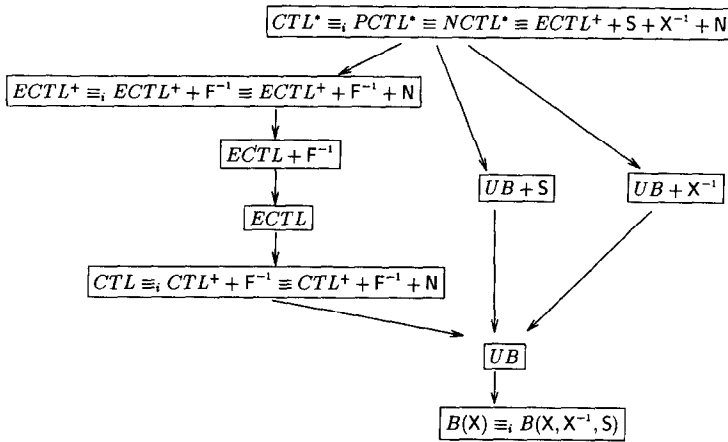


Fig. 1. A hierarchy of temporal logics with past

$PUB + N \equiv_i CTL$ and $ECTL + F^{-1} \prec_i ECTL + F^{-1} + N \prec_i ECTL^+ + F^{-1} + N \equiv_i ECTL^+$. Similarly, while $ECTL^+ + S + X^{-1} \prec_i PCTL^*$, we have

Theorem 6.7. $ECTL^+ + S + X^{-1} + N \equiv PCTL^* \equiv_i CTL^*$.

Proof. A corollary of the Normal Form Theorem [21, p. 296]. See the Appendix. \square

Fig. 1 summarizes the hierarchy we established. An arrow from L_1 to L_2 means that $L_1 \succ_i L_2$. No arrow can be added because $CTL \not\prec_i UB + S$ and $CTL \not\prec_i UB + X^{-1}$. Our proof that $EF(a \wedge EbUc \wedge Eb'Uc')$ (resp. $EaUb$) cannot be expressed modulo \equiv_i in $UB + S$ (resp. $UB + X^{-1}$) is beyond the scope of this article where the emphasis is on translatability through simple rewrite rules.

7. Conclusion

In this paper, we investigated which past-time combinators can be added to which branching-time temporal logics with the conflicting aims of

- enhancing practical expressivity,
- having translation algorithms into pure-future branching-time logics, like CTL and $ECTL^+$.

We also proposed a new combinator, N for “From Now On” and showed how it allows simple formulations of some practical temporal properties.

In general, logics with past-time combinators can be translated into pure-future logics, provided one is willing to have CTL^* as a target. When CTL or $ECTL^+$ is the target, we proved that one can only add N and F^{-1} before loosing translatability.

We claim that $CTL + F^{-1} + N$ is convenient for specification and model-checking (through a simple translation procedure). Of course such an approach is not perfect. For example, it does not include the usual diagnostic mechanism one often finds in model-checking tools. More importantly, complexity issues sometimes make the whole scheme unapplicable (by complexity, we mean the *size* of a pure-future formula equivalent to a given formula). This problem was not investigated in this study because we conjecture that our translation from $CTL + F^{-1}$ into CTL is nonelementary, exactly like Gabbay's translation for $PTL + Past$ is likely to be. In actual practice, this potential combinatorial explosion does not occur frequently, and all formulas in the Lift example of [16] have quickly been translated automatically. This is probably because these formulas have a low modal height. However it seems difficult to pinpoint a sensible fragment of $CTL + F^{-1} + N$ for which no explosion will occur: the formula $EF(F^{-1}a_1 \wedge \dots \wedge F^{-1}a_n)$ has modal height 2, and is initially equivalent to the CTL^+ formula $E(Fa_1 \wedge \dots \wedge Fa_n)$ for which no CTL equivalent of size less than $n!$ seems to exist.

Topics deserving further studies are (among others):

Axiomatizations for temporal logics with N. Given a complete axiomatization for CTL^* , it is easy to get complete axiomatizations for $NCTL^*$ by providing axioms for the separation of formulas. But it would be interesting to study axiomatizations capturing natural way of reasoning with past-time combinators and N .

Extensions of the separation methods. The separation methods we developed for branching-time logics should be investigated in the contexts of noninterleaving temporal logics, of interval temporal logics, of real-time temporal logics, ...

Modal logics of reactive systems. We already investigated in [17] how these methods can be used for modal logics characterizing behavioral equivalences of reactive systems. This research direction has many possible prolongations.

Appendix

Proof of Theorem 4.2

Lemma A.1. $E(s \vee aUb)Ur$ can be expressed in $UB + S$.

Proof. The idea is to state that r can be reached (EFr) in a way where all previously encountered states satisfy s or aUb . It is enough to ensure $s \vee a \vee b$ all along, provided that all $a \wedge \neg b \wedge \neg s$ states satisfy aUb (along the selected future). Then, the configuration to avoid is a past state satisfying $\neg a \wedge \neg b$ and $(\neg b)S(\neg b \wedge \neg s)$. This is essentially what we express in $UB + S$ through the following:

$$\begin{aligned}
 E(s \vee aUb)Ur &\equiv_i \vee EF \left(EXb \wedge aS \left[r \wedge a \wedge \neg F^{-1} \left(\neg a \wedge \neg b \wedge (\neg b)S(\neg b \wedge \neg s) \right) \right] \right) \\
 &\equiv_i \vee EF \left(EX(r \wedge b) \wedge \neg F^{-1} \left(\neg a \wedge \neg b \wedge (\neg b)S(\neg b \wedge \neg s) \right) \right) \\
 &\equiv_i \vee EF \left(\neg F^{-1} \left(\neg a \wedge \neg b \wedge (\neg b)S(\neg b \wedge \neg s) \right) \wedge EX(r) \wedge \neg (\neg b)S(\neg b \wedge \neg s) \right)
 \end{aligned}$$

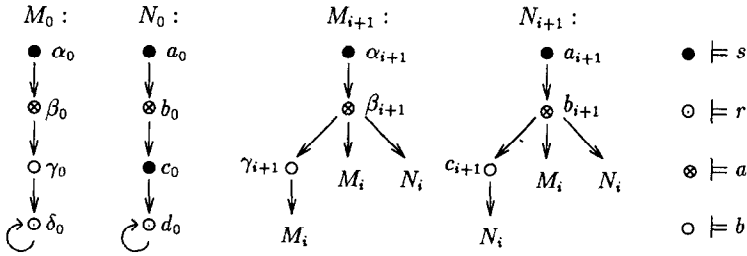


Fig. 2. A family $M_0, M_1, \dots, N_0, N_1, \dots$ of Kripke structures.

where the added complexity deals with various special cases, mostly regarding the position of the last required b before of after the r state. \square

We now need to prove that $E(s \vee aUb)Ur$ cannot be expressed in $ECTL^+$. This uses combinatorial techniques inspired from [11]. Consider the family of Kripke structures M_0, M_1, \dots and N_0, N_1, \dots given in Fig. 2.

Where the “color” indicates which propositions hold in which states. Observe that $\alpha_i \models E(s \vee aUb)Ur$ and $a_i \not\models E(s \vee aUb)Ur$ for all $i = 0, 1, \dots$. However, writing $|f|$ for the size of a formula f , we have

Lemma A.2. For all $f \in CTL$, and all $i \geq |f|$,

$$\begin{aligned} \alpha_i \models f & \text{ iff } a_i \models f, \\ \beta_i \models f & \text{ iff } b_i \models f, \\ \gamma_i \models f & \text{ iff } c_i \models f. \end{aligned}$$

Proof. By structural induction on f as in [11]. \square

Now there remains to extend the previous lemma to cover $ECTL^+$ and not just CTL .

Lemma A.3. For all f in $ECTL^+$, there is a f^* in CTL s.t. f and f^* are equivalent over all states of Fig. 2.

Proof. By induction on f . The interesting case is when f has the form

$$f = E(g \wedge \overset{\infty}{F} \varphi_1 \wedge \dots \wedge \overset{\infty}{F} \varphi_n \wedge \overset{\infty}{G} \psi)$$

with $Eg, \psi, \varphi_1, \dots, \varphi_n$ in CTL^+ . Because in the structures of Fig. 2 all runs eventually end up looping (on d_0 or δ_0), f is equivalent (in these models) to $E(g \wedge \overset{\infty}{F} \text{AG}(\varphi_1 \wedge \dots \wedge \varphi_n \wedge \psi))$ which is a CTL^+ formula. There only remains to transform this into a CTL formula and we are done. \square

Proof of Theorem 4.3

Theorem 4.3 is proved by establishing a separation lemma for $B(\mathbf{X}, \mathbf{X}^{-1}, \mathbf{S})$. Afterward, it is enough to apply (4) on separated formulas. (Here we use the partial separation notion from Section 5.)

Lemma A.4 (Separation lemma for $B(\mathbf{X}, \mathbf{X}^{-1}, \mathbf{S})$). *Any $f \in B(\mathbf{X}, \mathbf{X}^{-1}, \mathbf{S})$ formula f is (globally) equivalent to a separated $f' \in B(\mathbf{X}, \mathbf{X}^{-1}, \mathbf{S})$.*

Proof. By structural induction. The induction step is obvious when f has the form a , $\neg g$ or $f_1 \wedge f_2$. When f is some $\mathbf{X}^{-1}g$ or $f_1 \mathbf{S} f_2$, the induction hypothesis gives us an equivalent $\mathbf{X}^{-1}g'$ or $f'_1 \mathbf{S} f'_2$ which is separated. Finally, because $\mathbf{A}\mathbf{X}g \equiv \neg \mathbf{E}\mathbf{X}\neg g$, it is enough to only consider the case where f has the form $\mathbf{E}\mathbf{X}g$.

Assume then that f is some $\mathbf{E}\mathbf{X}g$. By ind. hyp., g is equivalent to a separated g' . With boolean manipulations, g' can be written as

$$g' \equiv \bigvee_i (\varphi_i^+ \wedge \psi_{i,1} \wedge \dots)$$

where the φ_i^+ 's are pure-future and the $\psi_{i,j}$'s are separated formulas of the form $\mathbf{X}^{-1}\psi$, or $\neg \mathbf{X}^{-1}\psi$, or $\psi \mathbf{S} \psi'$, or $\neg(\psi \mathbf{S} \psi')$. Using

$$\begin{aligned} f \mathbf{S} g &\equiv g \vee f \wedge \mathbf{X}^{-1}(f \mathbf{S} g) \\ \neg \mathbf{X}^{-1} f &\equiv \neg \mathbf{X}^{-1} \top \vee \mathbf{X}^{-1} \neg f \\ \mathbf{X}^{-1} f \wedge \mathbf{X}^{-1} g &\equiv \mathbf{X}^{-1}(f \wedge g) \end{aligned}$$

(and the fact that these equations respect separation), we can write g' as

$$g' \equiv \bigvee_i (\varphi_i^+ \wedge \mathbf{X}^{-1} \psi_i \{ \wedge \neg \mathbf{X}^{-1} \top \})$$

where the $\{\dots\}$ notation means that $\neg \mathbf{X}^{-1} \top$ may or may not appear (depending on i). Then $\mathbf{E}\mathbf{X}g'$ is easily rewritten into a separated formula, thanks to

$$\begin{aligned} \mathbf{E}\mathbf{X}(\bigvee_i g_i) &\equiv \bigvee_i \mathbf{E}\mathbf{X}g_i \\ \mathbf{E}\mathbf{X}(\varphi^+ \wedge \mathbf{X}^{-1}\psi) &\equiv \psi \wedge \mathbf{E}\mathbf{X}\varphi^+ \\ \mathbf{E}\mathbf{X}(\neg \mathbf{X}^{-1} \top \wedge \dots) &\equiv \perp \quad \square \end{aligned}$$

Proof of Lemma 5.2 and Theorem 5.1

The translation is done in several steps. We use contexts, i.e. $(CTL + F^{-1})$ formulas with variables in them. The x in $f[x]$ can be replaced by any $(CTL + F^{-1})$ formula: we

write $f[g]$ for f with g in place of x . Note that x may appear several times in $f[x]$. This is a key point in our method, used to collect copies of duplicated subformulas.

Lemma A.5. *If $f[x]$ is a pure-future context, then $f[F^{-1}x]$ is (globally) equivalent to a separated $f'[x, F^{-1}x]$ with $f'[x, y]$ a pure-future context.*

Proof. By structural induction on $f[x]$. Saying that $f[x]$ is pure-future is just saying that it is in *CTL*. We spend some time considering one case in detail:

- Assume $f[x]$ is some $E\varphi[x]U\psi[x]$. By ind. hyp., $\varphi[F^{-1}x]$ and $\psi[F^{-1}x]$ are equivalent to some separated $\varphi'[x, F^{-1}x]$ and $\psi'[x, F^{-1}x]$. Then $f[F^{-1}x] \equiv E\varphi'[x, F^{-1}x]U\psi'[x, F^{-1}x]$. In φ' and ψ' , $F^{-1}x$ can only appear under boolean combinators because of the separation property. We can use boolean manipulations to obtain

$$f[F^{-1}x] \equiv E\left((F^{-1}x \wedge \alpha) \vee (\neg F^{-1}x \wedge \beta) \vee \gamma\right) U\left((F^{-1}x \wedge \alpha') \vee (\neg F^{-1}x \wedge \beta') \vee \gamma'\right) \quad (\text{A.1})$$

where $\alpha, \beta, \gamma, \alpha', \beta'$ and γ' are pure-future. Then we use distributivity

$$EgU(h \vee h') \equiv (EgUh) \vee (EgUh')$$

to further simplify (A.1). We obtain several “E_U_” formulas with at most three occurrences of $F^{-1}x$. There we use the following five rewrite rules to extract $F^{-1}x$ from the scope of the U:

$$(R1) \quad E\gamma U(\alpha' \wedge F^{-1}x) \equiv F^{-1}x \wedge E\gamma U\alpha' \vee E\gamma U(x \wedge E\gamma U\alpha')$$

$$(R2) \quad E\gamma U(\beta' \wedge \neg F^{-1}x) \equiv \neg F^{-1}x \wedge E(\gamma \wedge \neg x) U(\beta' \wedge \neg x)$$

$$(R3) \quad E\left((\alpha \wedge F^{-1}x) \vee (\beta \wedge \neg F^{-1}x) \vee \gamma\right) U\gamma' \\ \equiv F^{-1}x \wedge E(\alpha \vee \gamma) U\gamma' \vee \neg F^{-1}x \wedge E\left(\neg x \wedge (\beta \vee \gamma)\right) U\gamma' \\ \vee \neg F^{-1}x \wedge E\left(\neg x \wedge (\beta \vee \gamma)\right) U\left(x \wedge E(\alpha \vee \gamma) U\gamma'\right)$$

$$(R4) \quad E\left((\alpha \wedge F^{-1}x) \vee (\beta \wedge \neg F^{-1}x) \vee \gamma\right) U(\alpha' \wedge F^{-1}x) \\ \equiv F^{-1}x \wedge E(\alpha \vee \gamma) U\alpha' \vee \neg F^{-1}x \wedge E\left(\neg x \wedge (\beta \vee \gamma)\right) U\left(x \wedge E(\alpha \vee \gamma) U\alpha'\right)$$

$$(R5) \quad E\left((\alpha \wedge F^{-1}x) \vee (\beta \wedge \neg F^{-1}x) \vee \gamma\right) U(\beta' \wedge \neg F^{-1}x) \\ \equiv \neg F^{-1}x \wedge E\left(\neg x \wedge (\beta \vee \gamma)\right) U(\beta' \wedge \neg x)$$

- Assume $f[x]$ is some $EX\varphi[x]$. We proceed similarly. Using the ind. hyp. and distributivity

$$EX(h \vee h') \equiv EXh \vee EXh'$$

lead to a situation where we only need the following rules:

$$(R6) \quad \mathbf{EX}(\alpha \wedge \mathbf{F}^{-1}x) \equiv \mathbf{EX}(\alpha \wedge x) \vee \mathbf{F}^{-1}x \wedge \mathbf{EX}\alpha$$

$$(R7) \quad \mathbf{EX}(\alpha \wedge \neg \mathbf{F}^{-1}x) \equiv \mathbf{EX}(\alpha \wedge \neg x) \wedge \neg \mathbf{F}^{-1}x$$

- Assume $f[x]$ is some $\mathbf{EG}\varphi[x]$. Then $f[\mathbf{F}^{-1}x] \equiv \mathbf{EG}\varphi'[x, \mathbf{F}^{-1}x]$. Because of the separation assumption, w.l.o.g. we can write $\mathbf{EG}\varphi'[x, \mathbf{F}^{-1}x]$ under the general form

$$f[\mathbf{F}^{-1}x] \equiv \mathbf{EG}\left((\alpha \wedge \mathbf{F}^{-1}x) \vee (\beta \wedge \neg \mathbf{F}^{-1}x) \vee \gamma\right) \tag{A.2}$$

Then we only need the following rule:

$$(R8) \quad \mathbf{EG}\left((\alpha \wedge \mathbf{F}^{-1}x) \vee (\beta \wedge \neg \mathbf{F}^{-1}x) \vee \gamma\right) \equiv \bigvee_{\neg \mathbf{F}^{-1}x \wedge} \mathbf{F}^{-1}x \wedge \mathbf{EG}(\alpha \vee \gamma) \left(\begin{array}{l} \mathbf{EG}(\neg x \wedge (\beta \vee \gamma)) \\ \mathbf{E}(\neg x \wedge (\beta \vee \gamma)) \mathbf{U}(\alpha \wedge \mathbf{EG} \\ (\alpha \vee \gamma)) \end{array} \right)$$

- Finally, the other cases are obvious, or can be reduced to what we saw through $\mathbf{AX}h \equiv \neg \mathbf{EX}\neg h$ and $\mathbf{AG}Uh \equiv \neg \mathbf{EG}\neg h \wedge \neg (\mathbf{E}\neg h \mathbf{U}\neg g \wedge \neg h)$.

We let the reader check that equations (R1)–(R8) are correct.⁷ \square

Lemma A.6. *If $f[x_1, \dots, x_n]$ is a pure-future context, then $f[\mathbf{F}^{-1}x_1, \dots, \mathbf{F}^{-1}x_n]$ is equivalent to a separated $f'[x_1, \mathbf{F}^{-1}x_1, \dots, x_n, \mathbf{F}^{-1}x_n]$ with $f'[x_1, y_1, \dots, x_n, y_n]$ a pure-future context.*

Proof. By induction on n , using Lemma A.5. \square

Lemma A.7. *If $f[x_1, \dots, x_n]$ is a pure-future context and $\psi_1^-, \dots, \psi_n^-$ are pure-past CTL + \mathbf{F}^{-1} formulas (i.e. formulas with \mathbf{F}^{-1} as the only temporal combinator), then $f[\psi_1^-, \dots, \psi_n^-]$ is equivalent to a separated CTL + \mathbf{F}^{-1} formula.*

Proof. By induction on the maximum number of nested \mathbf{F}^{-1} 's in the ψ_i^- 's and using Lemma A.6. \square

Lemma A.8. *If $f[x_1, \dots, x_n]$ is a pure-future context and ψ_1, \dots, ψ_n are separated CTL + \mathbf{F}^{-1} formulas, then $f[\psi_1, \dots, \psi_n]$ is equivalent to a separated CTL + \mathbf{F}^{-1} formula.*

⁷This should not be too difficult. Alternatively, all five rules (R1)–(R5) could be replaced by a single general rule for which correctness is more difficult to assert.

Proof. Because it is separated, a ψ_i has the form $g_i^-[\varphi_{i,1}^+, \dots, \varphi_{i,m_i}^+]$ with pure-future $\varphi_{i,j}^+$'s and pure-past $g_i^-[x_1, \dots, x_{k_i}]$'s. Applying Lemma A.7 to $f[g_1^-[x_{1,1}, \dots, x_{1,m_1}], \dots, g_n^-[x_{n,1}, \dots, x_{n,m_n}]]$ yields a separated $f'[x_{1,1}, \dots, x_{n,m_n}]$. Then $f'[\varphi_{1,1}^+, \dots, \varphi_{n,m_n}^+]$ is separated and equivalent to $f[\psi_1, \dots, \psi_n]$. \square

Now we can prove Lemma 5.2 by structural induction on the $CTL + F^{-1}$ formula and using Lemma A.8. Then Theorem 5.1 is easy to prove: once we have a separated formula, we repeatedly use

$$F^{-1}\varphi \equiv_i \varphi$$

in boolean contexts.

Proof of Theorem 5.3

We slightly generalize the proof (from [10]) that $CTL^+ \equiv CTL$ to prove that $CTL^+ + F^{-1} \equiv CTL + F^{-1}$. Then Theorem 5.1 concludes the proof.

Lemma A.9. Any $CTL^+ + F^{-1}$ formula f is equivalent to a $CTL + F^{-1}$ formula.

Proof. By induction on f . The only interesting case is when f has the form

$$E \left(\bigwedge_i (f_i U g_i) \wedge \bigwedge_i \neg(f_i' U g_i') \wedge \bigwedge_i Xh_i \wedge \bigwedge_i F^{-1}k_i \wedge \neg F^{-1}k' \right)$$

where we have

$$f \equiv E \left(\bigwedge_i (f_i U g_i) \wedge \bigwedge_i \neg(f_i' U g_i') \wedge \bigwedge_i Xh_i \right) \wedge \bigwedge_i F^{-1}k_i \wedge \neg F^{-1}k'$$

Then $E(\bigwedge_i (f_i U g_i) \wedge \bigwedge_i \neg(f_i' U g_i') \wedge \bigwedge_i Xh_i)$ can be transformed into a $CTL + F^{-1}$ using exactly the techniques for rewriting a CTL^+ formula into a CTL formula [10]. \square

Proof of Theorem 5.4

We introduce an intermediary fragment:

$$L^\infty \ni f, g ::= a \mid f \wedge g \mid \neg f \mid EXf \mid EfUg \mid AfUg \mid F^{-1}f \mid E \left(Gf \wedge \bigwedge_i \overset{\infty}{F}g_i \right)$$

Then the proof of Theorem 5.4 is sketched as.

$$ECTL^+ + F^{-1} \equiv L^\infty \equiv L_{sep}^\infty \equiv_i ECTL^+$$

The first part is easy. Clearly, from a syntactical viewpoint $ECTL + F^{-1} \subseteq L^\infty \subseteq ECTL^+ + F^{-1}$, but we also have $ECTL^+ + F^{-1} \preceq_g L^\infty$:

Lemma A.10. Any $ECTL^+ + F^{-1}$ formula is equivalent to a formula in L^∞ . is easy.

Lemma A.11 (Separation lemma for L^∞). Any L^∞ is equivalent to a separated L^∞ formula.

Proof. We proceed as in the Separation Lemma for $CTL + F^{-1}$ (Lemma 5.2). In the crucial step where we prove that any $f[F^{-1}x]$ with $f[x]$ a pure-future L^∞ context can be separated, there is one more case to consider: when $f[x]$ has the form $E(G\varphi \wedge \bigwedge_i \psi_i)$. This needs one more rewrite rule.

$$\begin{aligned}
 & F^{-1}x \wedge E \left[G(\alpha \vee \gamma) \wedge \bigwedge_i F^\infty(\beta_i \vee \gamma_i) \right] \\
 E \left(\begin{array}{l} G \left[(F^{-1}x \wedge \alpha) \vee (\neg F^{-1}x \wedge \alpha') \vee \gamma \right] \\ \bigwedge_i F^\infty \left[(F^{-1}x \wedge \beta_i) \vee (\neg F^{-1}x \wedge \beta'_i) \vee \gamma_i \right] \end{array} \right) & \equiv \begin{array}{l} \vee \neg F^{-1}x \wedge E \left[G(\neg x \wedge (\alpha' \vee \gamma)) \right. \\ \left. \wedge \bigwedge_i F^\infty(\beta'_i \vee \gamma_i) \right] \\ \vee \neg F^{-1}x \wedge E(\neg x \wedge (\alpha' \vee \gamma)) \\ U \left(x \wedge E \left[G(\alpha \vee \gamma) \wedge \bigwedge_i F^\infty(\beta_i \vee \gamma_i) \right] \right) \quad \square \end{array}
 \end{aligned}$$

After this we can conclude immediately because the pure-future fragment of L^∞ is $ECTL^+$.

Proof of Theorem 5.5

To prove that $ECTL + F^{-1} \not\preceq_i ECTL$, first observe that $E(F^\infty p \wedge Gq) \equiv E F^\infty(p \wedge G^{-1}q)$. Now it is enough to prove that $E(F^\infty p \wedge Gq)$ cannot be expressed in $ECTL$. For this we consider the models $M_1, M_2, \dots, N_1, N_2, \dots$ described in Fig. 7. (They are inspired from the proofs that $E F^\infty p$ cannot be expressed in CTL and that $E(F^\infty p \wedge F^\infty q)$ cannot be expressed in $ECTL$ [11].)

Clearly, for any $i = 1, \dots$,

$$a_i \models E(F^\infty p \wedge Gq) \text{ and } \alpha_i \not\models E(F^\infty p \wedge Gq)$$

However, writing $|f|$ for the size of f , we show by induction on f (left to the reader) that

- $\alpha_i \models f$ iff $a_i \models f$,
- $\beta_i \models f$ iff $b_i \models f$,
- $\gamma_i \models f$ iff $c_i \models f$.

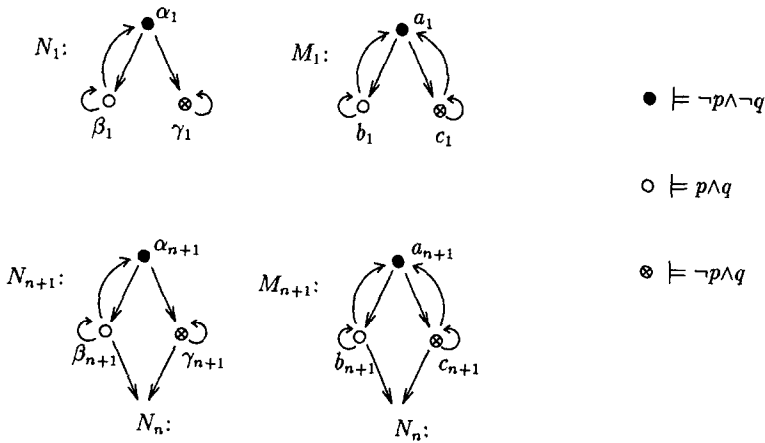


Fig. 3. $a_i, \alpha_i \models p \wedge q$, $b_i, \beta_i \models \neg p \wedge \neg q$, $c_i, \gamma_i \models \neg p \wedge q$.

for all $f \in ECTL$ and all $i \geq |f|$.

Then, to prove that $ECTL^+ \not\equiv_i ECTL + F^{-1}$, we prove that $E(\bar{F} p \wedge \bar{F} q)$ is not (initially) equivalent to any $ECTL + F^{-1}$ formula. First, we observe that $E(\bar{F} p \wedge \bar{F} q)$ cannot be expressed in the following pure-future fragment of $ECTL^+$:

$$L \ni f, g ::= a \mid f \wedge g \mid \neg f \mid EXf \mid EfUg \mid AfUg \mid E(\bar{F} f \wedge Gg)$$

Clearly $ECTL \subseteq L \subseteq ECTL^+$. The proof that $E(\bar{F} p \wedge \bar{F} q)$ cannot be expressed in L can be done simply by enriching (left to the reader) the proof from [11] that $E(\bar{F} p \wedge \bar{F} q)$ cannot be expressed in $ECTL$. The same models work for L as well.

Because $ECTL + F^{-1} \subseteq L + F^{-1}$, it is now sufficient to have a separation theorem for $L + F^{-1}$, so that we shall arrive at

$$ECTL + F^{-1} \subseteq L + F^{-1} \equiv (L + F^{-1})_{sep} \equiv_i L \prec ECTL^+$$

Lemma A.12 (Separation theorem for $L + F^{-1}$). *Any $ECTL + F^{-1}$ formula is equivalent to a separated $L + F^{-1}$ formula.*

is a special case of Lemma A.11 and can be proved using the same transformations.

Proof of Theorem 6.7

The Normal Form Theorem [21] states that any PTL formula is initially equivalent to a formula of the form

$$\bigwedge_{i=1}^n (\bar{F} \varphi_i \vee \bar{G} \psi_i)$$

where the φ_i 's and the ψ_i 's are pure-past (linear-time) formulas.

With this, it is easy to translate any formula f in CTL^* into a globally equivalent $B(\mathbf{F}, \mathbf{X}^{-1}, \mathbf{S}, \wedge, \neg) + \mathbf{N}$ formula. The interesting case is when f is some Eg . Then we replace in g all subformulas of the form Eh by new atomic propositions. This yields a PTL formula g' which can be written as some $\bigwedge_{i=1}^n (\mathbf{F} \varphi_i \vee \mathbf{G} \psi_i)$. Then

$$Eg' \equiv \mathbf{NE} \bigwedge_{i=1}^n (\mathbf{F} \varphi_i \vee \mathbf{G} \psi_i)$$

It now remains to replace the atomic propositions we introduced by their $B(\mathbf{F}, \mathbf{X}^{-1}, \mathbf{S}, \wedge, \neg) + \mathbf{N}$ equivalents, and we are done.

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